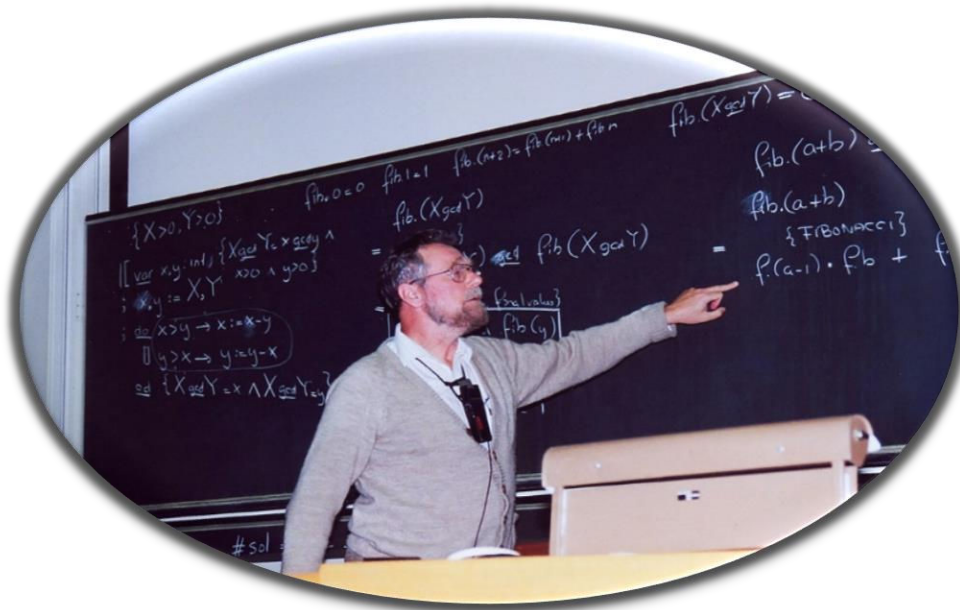


## DIJKSTRA'S ALGORITHM

- **Dijkstra's algorithm** is a popular algorithm in computer science and graph theory, designed to find the **shortest path** between a starting vertex and all other vertices in a weighted graph with non-negative edge weights.
- It was conceived by Dutch computer scientist **Edsger Dijkstra** in **1956** and is commonly used in applications such as routing and network protocols.



### Requirements :

- **Dijkstra's Algorithm** can only work with graphs that have positive weights.
- This is because, during the process, the weights of the edges have to be added to find the shortest path.
- If there is a negative weight in the graph, then the algorithm will not work properly
- Once a node has been marked as "visited", the current path to that node is marked as the shortest path to reach that node.
- And negative weights can alter this if the total weight can be decremented after this step has occurred.

## Dijkstra's Algorithm Complexity

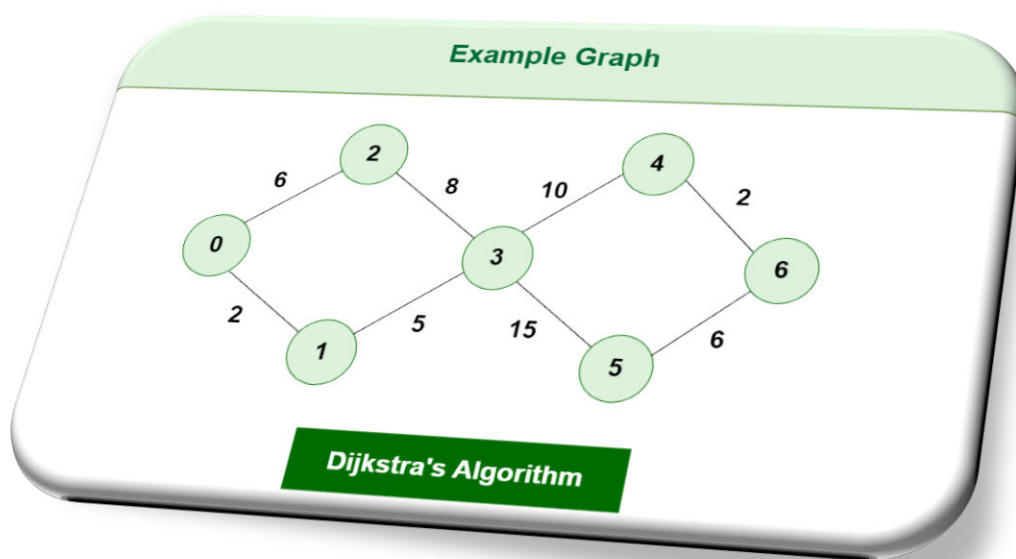
- **Time Complexity:**  $O(E \log V)$

where, E is the number of edges and V is the number of vertices.

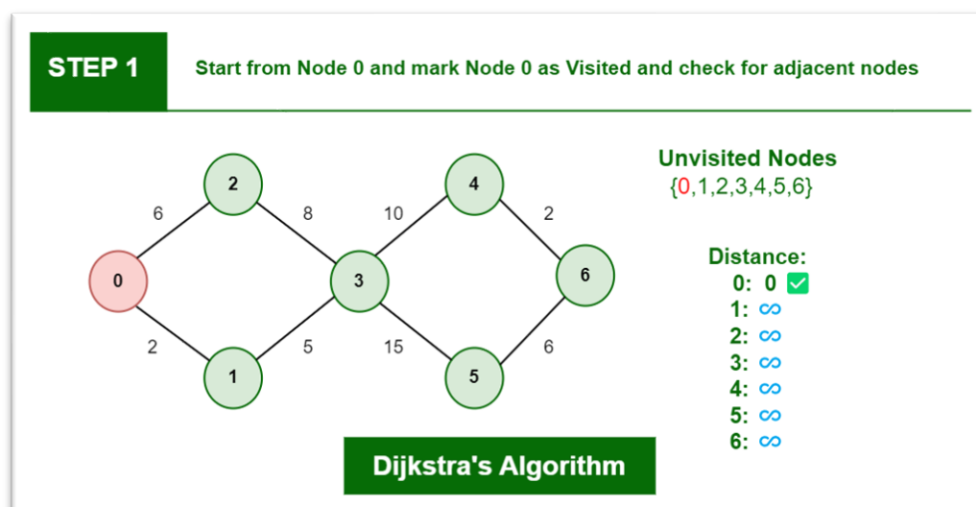
- **Space Complexity:**  $O(V)$

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## How does Dijkstra's Algorithm works?

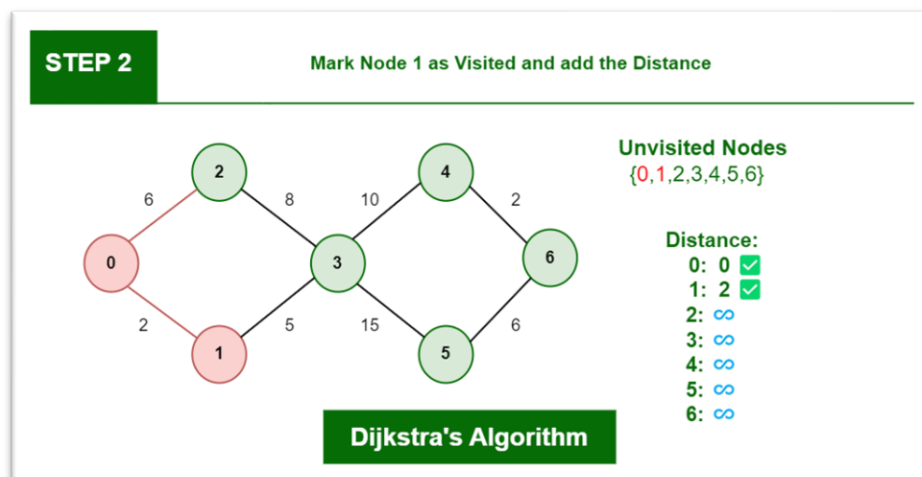


**Step 1:** Start from Node 0 and mark Node as visited as you can check in below image visited Node is marked red.



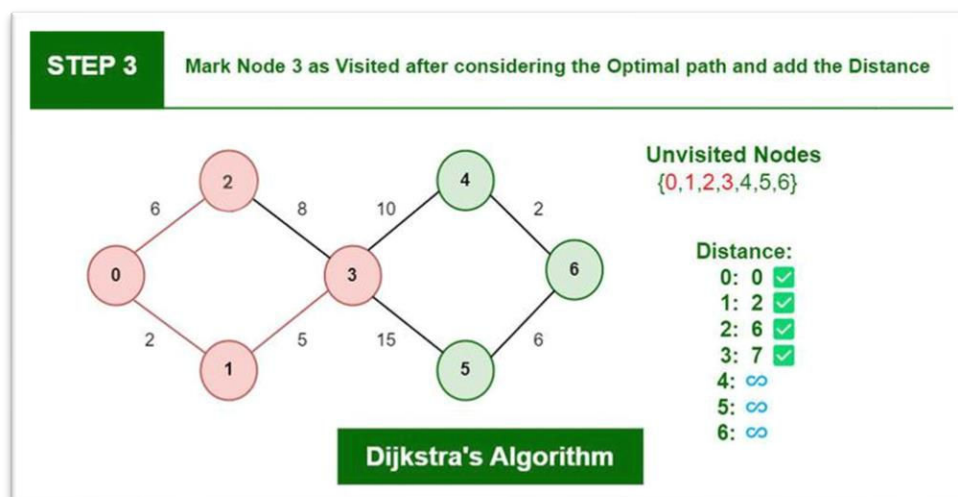
**Step 2:** Check for adjacent Nodes, Now we have to choices (Either choose Node 1 with distance 2 or either choose Node 2 with distance 6 ) and choose Node with minimum distance. In this step Node 1 is Minimum distance adjacent Node, so marked it as visited and add up the distance.

**Distance: Node 0 -> Node 1 = 2**



**Step 3:** Then Move Forward and check for adjacent Node which is Node 3, so marked it as visited and add up the distance, Now the distance will be:

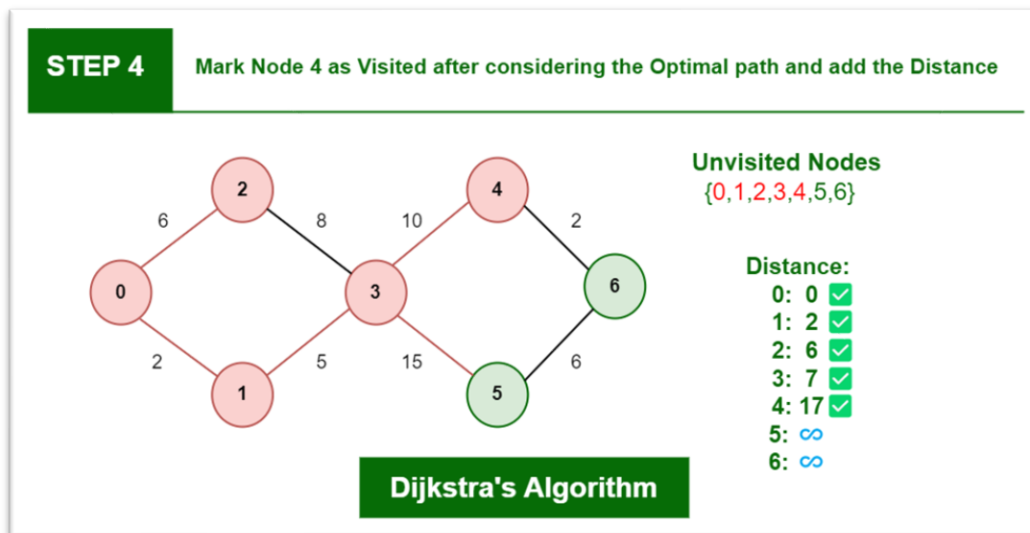
**Distance: Node 0 -> Node 1 -> Node 3 = 2 + 5 = 7**



**Step 4:** Again we have two choices for adjacent Nodes (Either we can choose Node 4 with distance 10 or either we can choose Node 5 with distance 15) so choose Node with minimum distance. In this step Node 4 is Minimum distance adjacent Node, so marked it as visited and add up the distance.

**Distance: Node 0 -> Node 1 -> Node 3 -> Node 4 = 2 + 5 + 10 = 17**

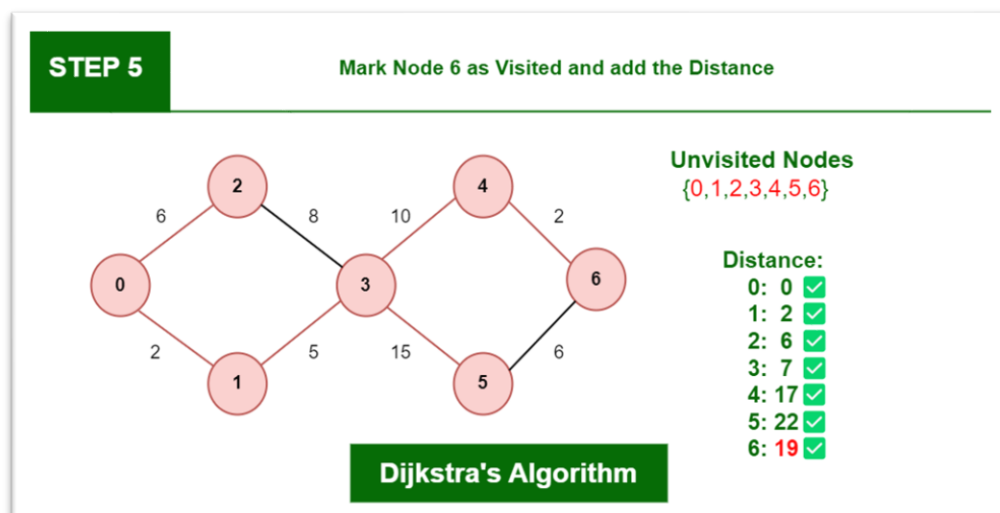
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**Step 5:** Again, Move Forward and check for adjacent Node which is **Node 6**, so marked it as visited and add up the distance, Now the distance will be:

**Distance:**

**Node 0 -> Node 1 -> Node 3 -> Node 4 -> Node 6 = 2 + 5 + 10 + 2 = 19**



So, the Shortest Distance from the Source Vertex is **19** which is optimal one

### Algorithm for Dijkstra's Algorithm:

1. Mark the source node with a current distance of 0 and the rest with infinity.
2. Set the non-visited node with the smallest current distance as the current node.
3. For each neighbor, N of the current node adds the current distance of the adjacent node with the weight of the edge connecting 0->1. If it is smaller than the current distance of Node, set it as the new current distance of N.
4. Mark the current node 1 as visited.
5. Go to step 2 if there are any nodes are unvisited.

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### Implementation of Dijkstra's Algorithm:

```
#include <bits/stdc++.h>
using namespace std;
#define INF 0x3f3f3f3f
// iPair ==> Integer Pair
typedef pair<int, int> iPair;

class Graph {
    int V; // No. of vertices
    list<pair<int, int> >* adj;
public:
    Graph(int V); // Constructor
```

```

// function to add an edge to graph
void addEdge(int u, int v, int w);

// prints shortest path from s
void shortestPath(int s);
};

// Allocates memory for adjacency list
Graph::Graph(int V)
{
    this->V = V;
    adj = new list<iPair>[V];
}

void Graph::addEdge(int u, int v, int w)
{
    adj[u].push_back(make_pair(v, w));
    adj[v].push_back(make_pair(u, w));
}

// Prints shortest paths from src to all other vertices
void Graph::shortestPath(int src)
{
    priority_queue<iPair, vector<iPair>, greater<iPair> > pq;

    // Create a vector for distances and initialize all
    // distances as infinite (INF)
    vector<int> dist(V, INF);

```

```

// Insert source itself in priority queue and initialize
// its distance as 0.
pq.push(make_pair(0, src));
dist[src] = 0;

/* Looping till priority queue becomes empty (or all
distances are not finalized) */
while (!pq.empty()) {
    int u = pq.top().second;
    pq.pop();
    // 'i' is used to get all adjacent vertices of a
    // vertex
    list<pair<int, int> >::iterator i;
    for (i = adj[u].begin(); i != adj[u].end(); ++i) {
        // Get vertex label and weight of current
        // adjacent of u.
        int v = (*i).first;
        int weight = (*i).second;
        // If there is shorter path to v through u.
        if (dist[v] > dist[u] + weight) {
            // Updating distance of v
            dist[v] = dist[u] + weight;
            pq.push(make_pair(dist[v], v));
        }
    }
}

```

```
// Print shortest distances stored in dist[]

    printf("Vertex Distance from Source\n");
    for (int i = 0; i < V; ++i)
        printf("%d \t\t %d\n", i, dist[i]);
}

// Driver program to test methods of graph class
int main()
{
    // create the graph given in above figure
    int V = 7;
    Graph g(V);
    // making above shown graph
    g.addEdge(0, 1, 2);
    g.addEdge(0, 2, 6);
    g.addEdge(1, 3, 5);
    g.addEdge(2, 3, 8);
    g.addEdge(3, 4, 10);
    g.addEdge(3, 5, 15);
    g.addEdge(4, 6, 2);
    g.addEdge(5, 6, 6);
    g.shortestPath(0);

    return 0;
}
```



### **Application of Dijkstra's Algorithm:**

- It is used in finding Shortest Path.
- It is used in geographical Maps.
- To find locations of Map which refers to vertices of graph.
- Distance between the location refers to edges.
- It is used in IP routing to find Open shortest Path First.
- It is used in the telephone network.